



# PUMA TL 2000 / 2500

High Productivity 4-Axis Turning Center



# High Productivity 4-Axis Turning Center

The Puma TL series of machines is engineered to increase productivity through high efficiency. As a process-integrated machine the TL provides a new level of performance and capabilities.

## PUMA TL 2000 / 2500





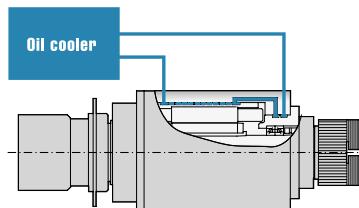
## Main Spindle

The powerful built in spindle motor allows for a wide range machining operations, from precise finishing to high powered metal removal using both turrets at the same time.



### Oil Cooling Unit for Spindles

Motor is surrounded by an oil jacket cooling system to minimize thermal displacement and ensure consistency through a wide range of cutting conditions.



### PUMA TL2000/2000M

Max. spindle speed

Motor (Int./Cont.)

**5000 r/min**

**22/15 kW**

### PUMA TL2500/2500M

Max. spindle speed

Motor (Int./Cont.)

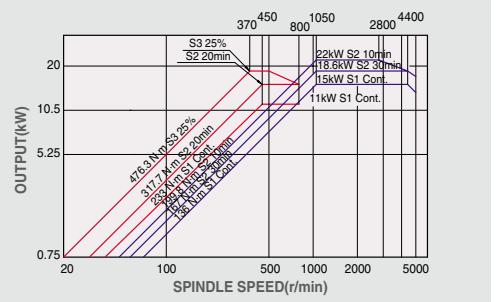
**4000 r/min**

**26/22 kW**

### PUMA TL2000/2000M

Spindle motor power : 22kW(Built-in)

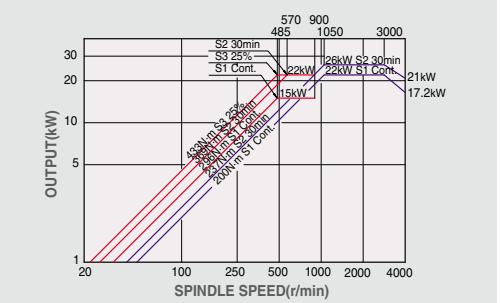
Max. Spindle speed : 5000 r/min



### PUMA TL2500/2500M

Spindle motor power : 26kW(Built-in)

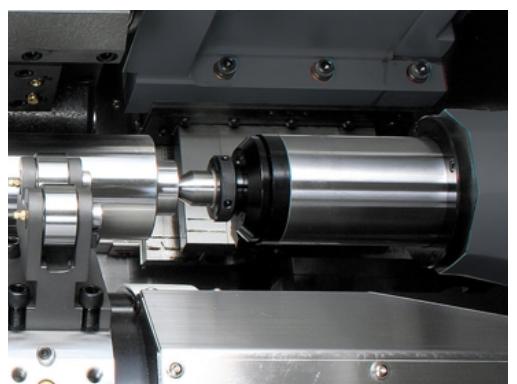
Max. Spindle speed : 4000 r/min



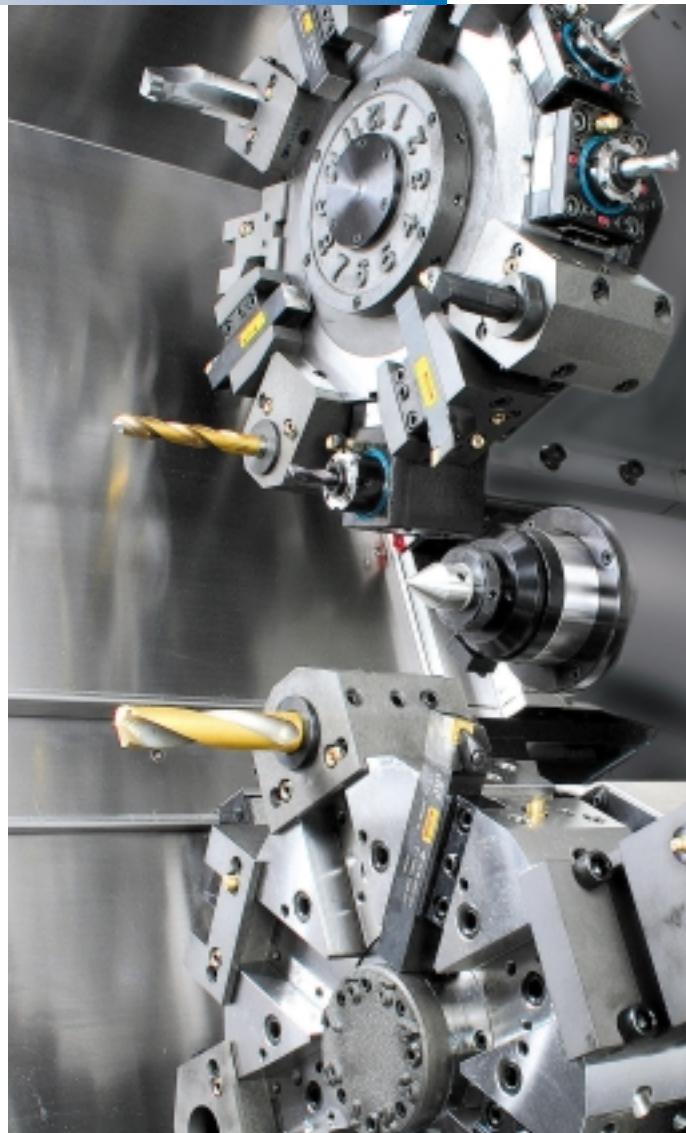
## Tail Stock

The widely spaced guide ways and heavy-duty tailstock design ensures ample rigidity. The tailstock is positioned by a drive bar that engages with the carriage.

Tail stock quill type	unit	MT#5
Tail stock quill diameter	mm	100
Tail stock quill travel	mm	120
Tail stock quill thrust force	kN	17



## Turret



Total 20 tool stations of upper (optional milling upper turret only TL2000M/2500M) and lower turrets make it possible to complete complicated parts requiring many tools in just one set-up. Reliable servo driven turrets reduce the total cycle time required to machine parts.

Index time (1-station swivel)	No. of tool station (Upper+Lower turret)
<b>0.15 s</b>	<b>20 stations(12+8)</b>

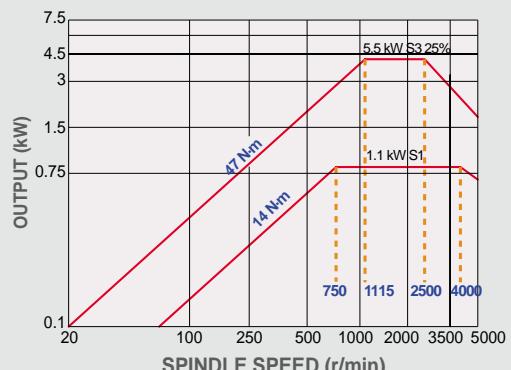
### Radial BMT



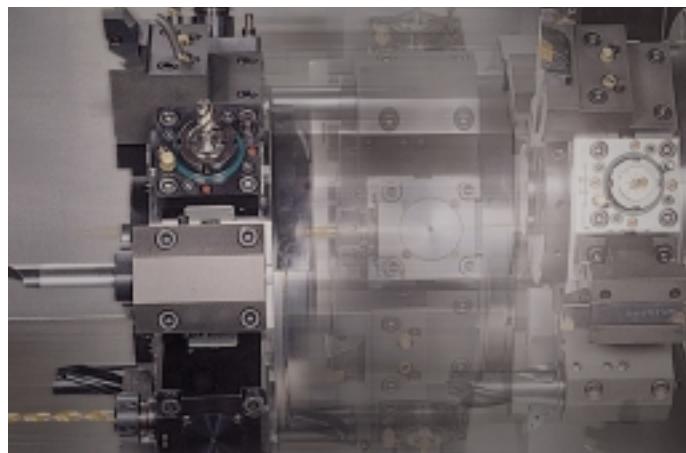
The turret features BMT55P style tooling in which the toolholders are mounted directly to the turrets periphery using 4 large bolts.

### Rotary tool spindle power-torque diagram

Max. speed : 5000 r/min



## Rapid Traverse



X-axis **20 m/min**

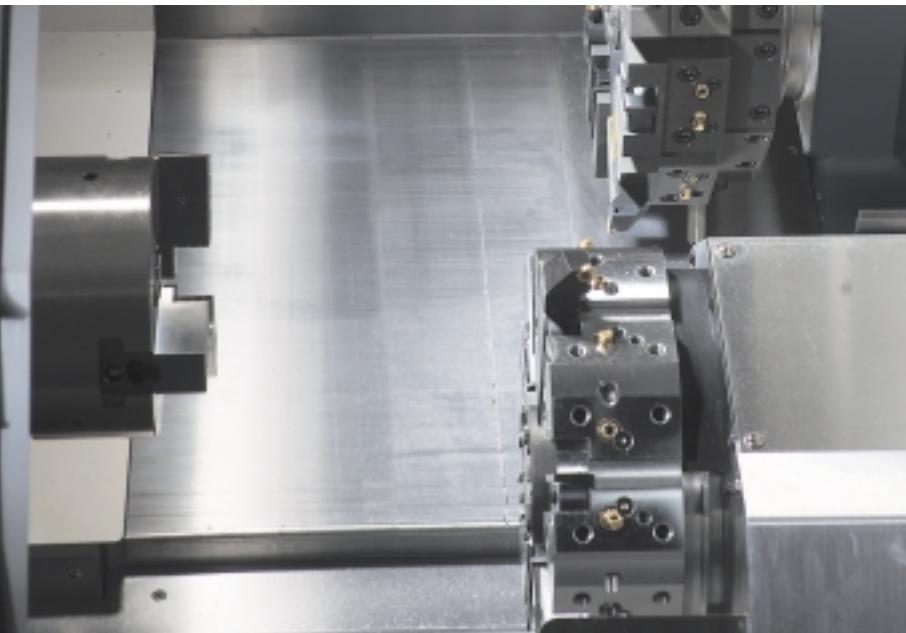
Z-axis **24 m/min**

Each axis is powered by a maintenance free digital AC servo motor. These high torque drive motors are connected to the ball screws without intermediate gears for quiet and responsive slide movement with virtually no backlash.



## Machine Construction

The combining of a high performance integral spindle motor with upper and lower multi-axis turrets yields a machine perfectly engineered for high productivity and optimum efficiency.

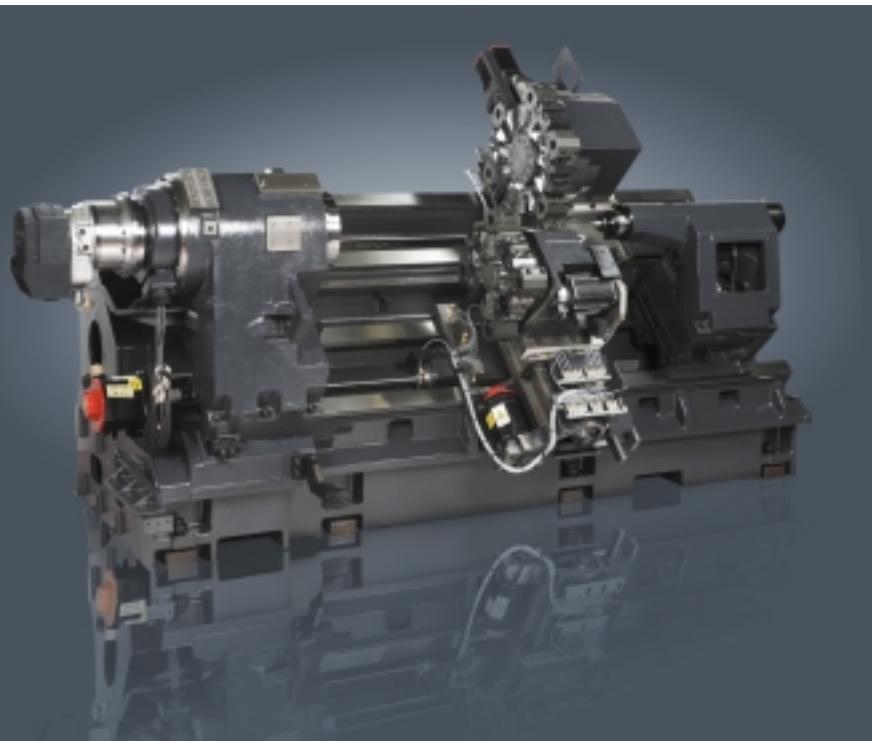


Shown with milling option

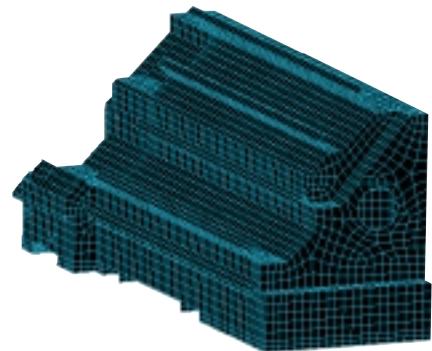
4-axis linear controlled machine establishes multi-axis functional performance with simultaneous control of both turrets for middle diameter shaft workpieces

## Robust Design

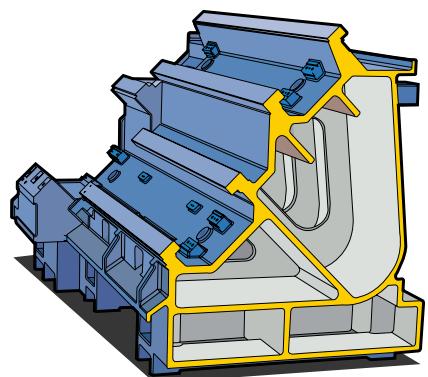
The heavily ribbed triangular torque frame resists eccentric loads. A 45° inclined wall is inserted into triangular frame under the center of the frame, to endure high stress due to X direction forces.



### FEM Structural Analysis

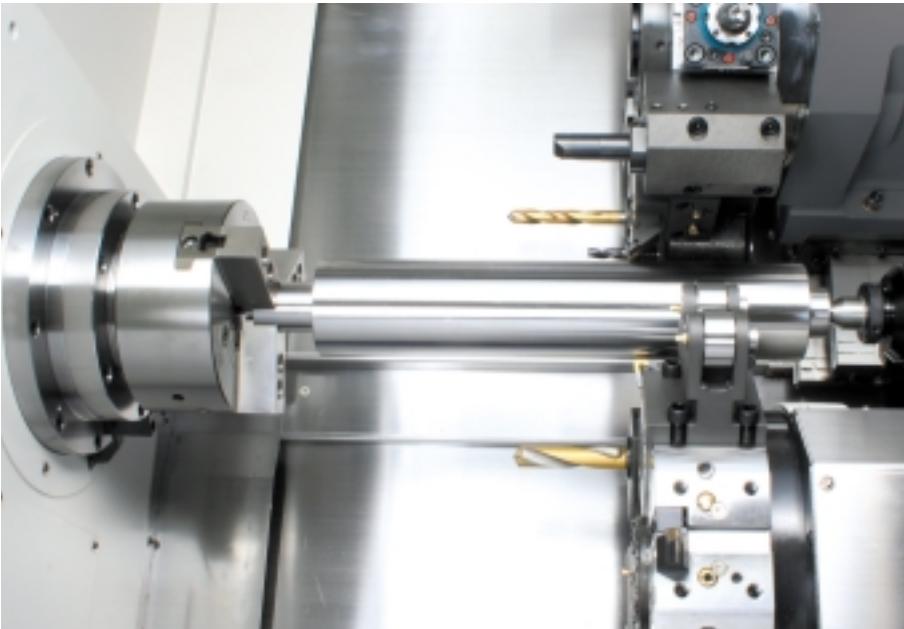


### Torque Tube of Triangular Frame

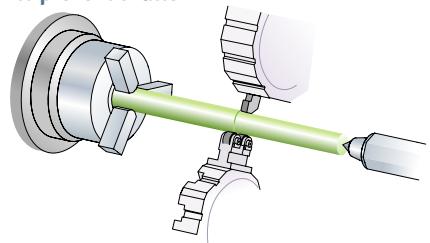


# Machining Flexibility

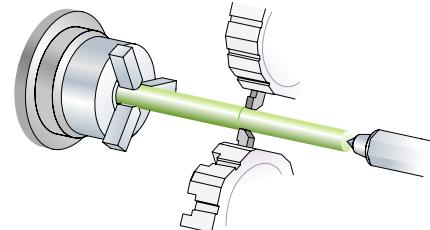
- Accuracy and time savings by virtue of a single set-up.
- Unmanned operation by automation support.
- Less floor space and increased productivity.



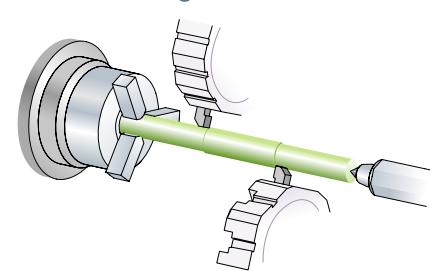
Long shaft working by follow rest operation to prevent chatter



Balanced turning by 4-axis

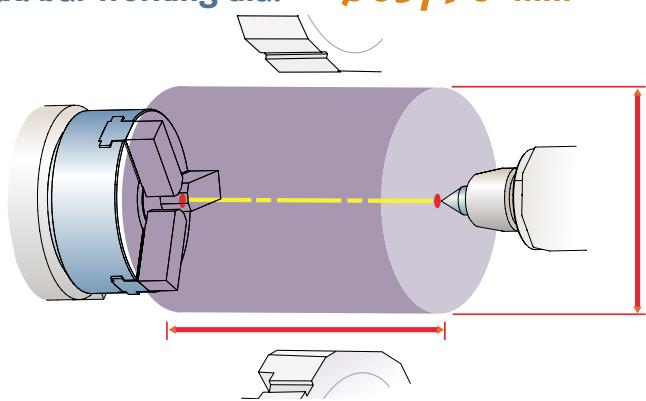


Simultaneous 4-axis turning



## Working Range

Max. bar working dia. **Ø65/76\*** mm



A : Max. turning dia.

**370\*\*** mm (on upper turret)

**240\*\*** mm (on lower turret)

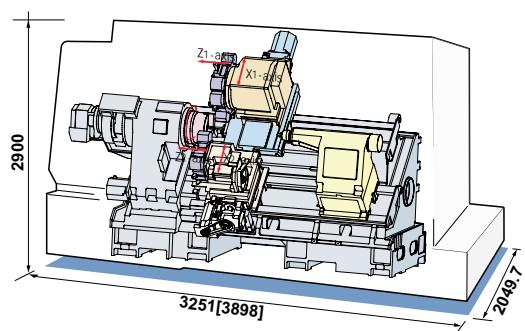
B : Max. turning length

**600 [1000]** mm

\* : on TL2500 series, [ ] : Long bed models

\*\* : on TL2000[L] / TL2500[L]

## Systemized Compact Structure



## Travel

X1-axis

**250** mm

Z1-axis

**650 [1050]** mm

X2-axis

**150** mm

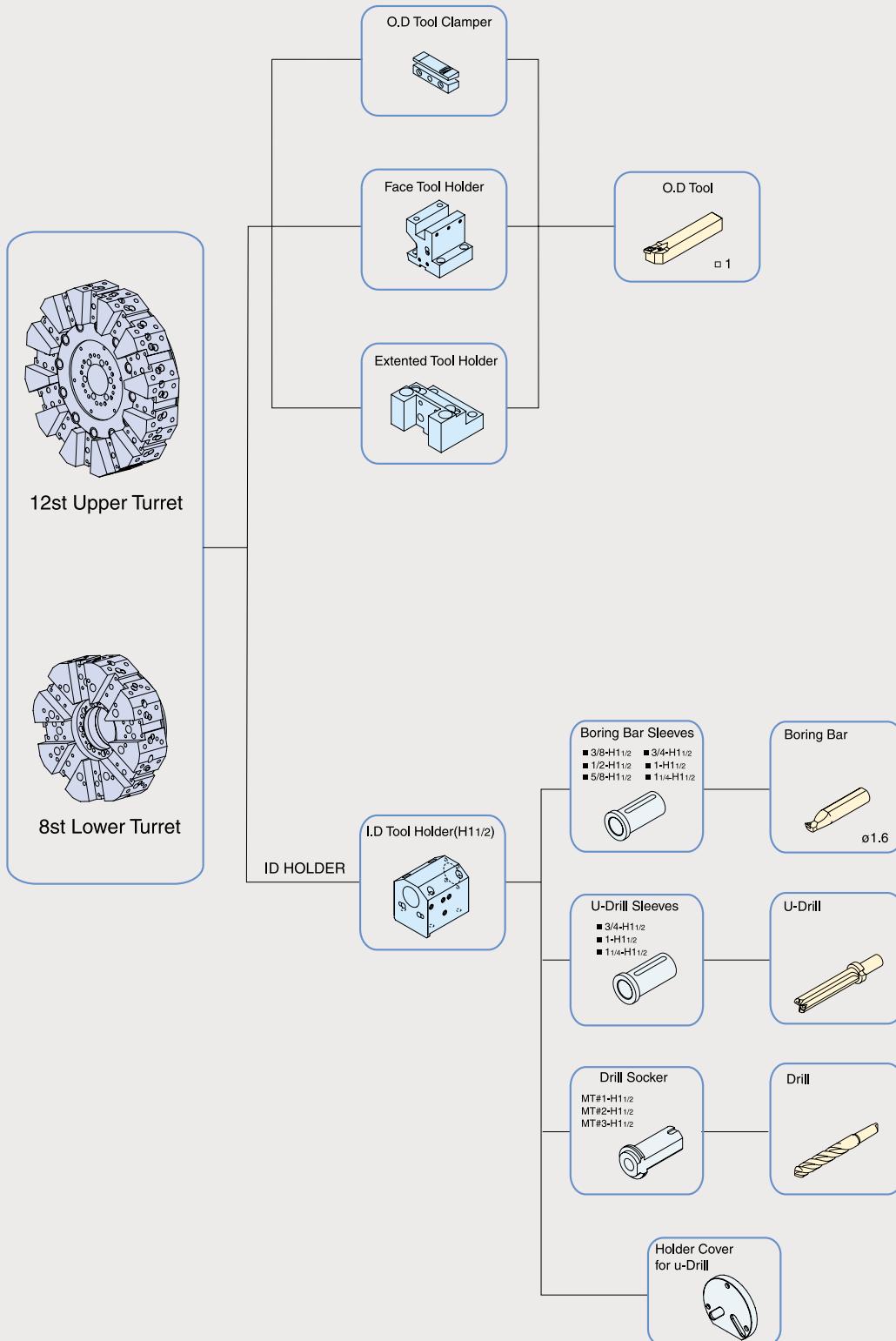
Z2-axis

**630 [1030]** mm

# Tooling System (Upper & Lower Turret)

unit : mm

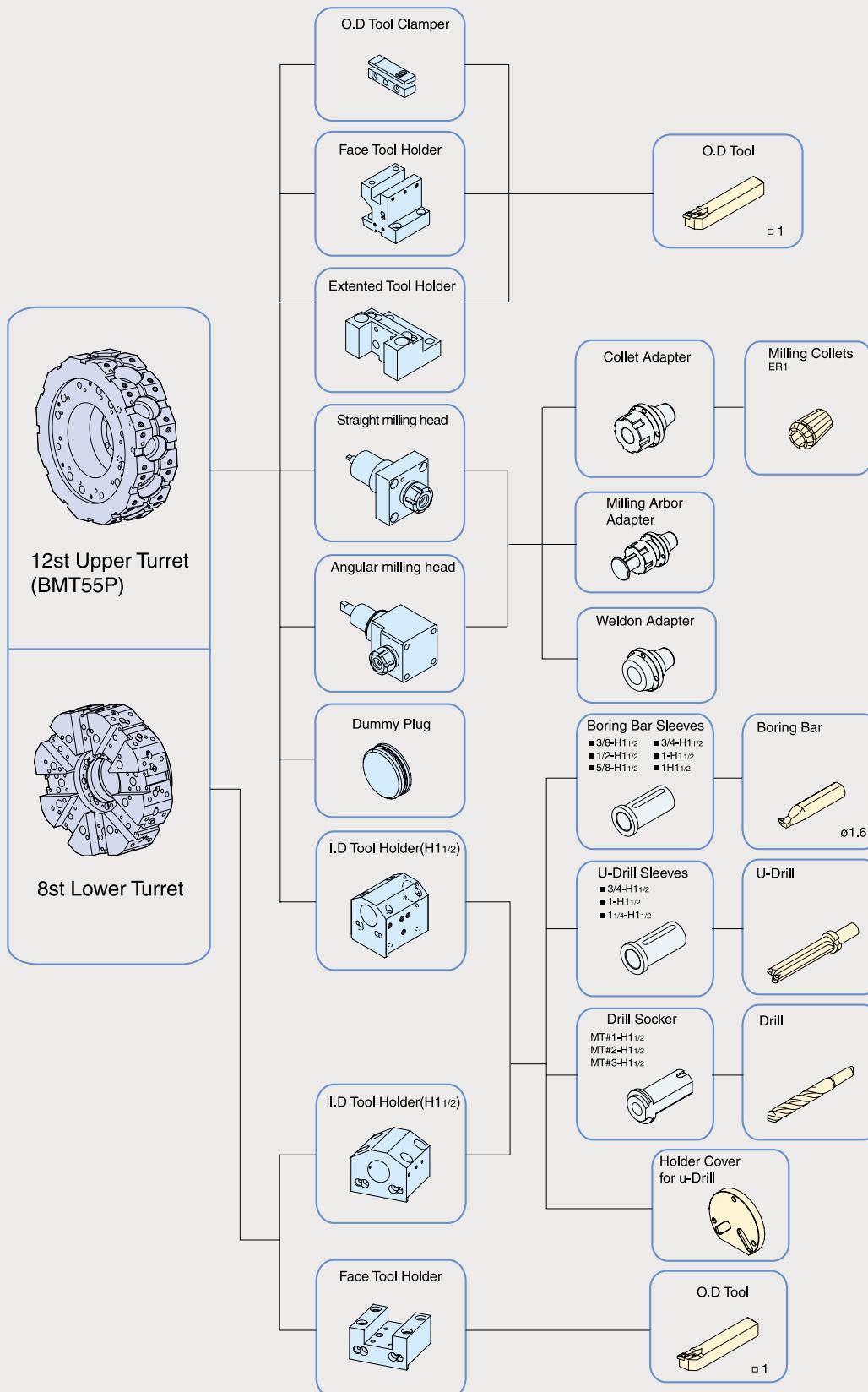
## PUMA TL 2000/2500



# Tooling System (Upper & Lower Turret)

unit : mm

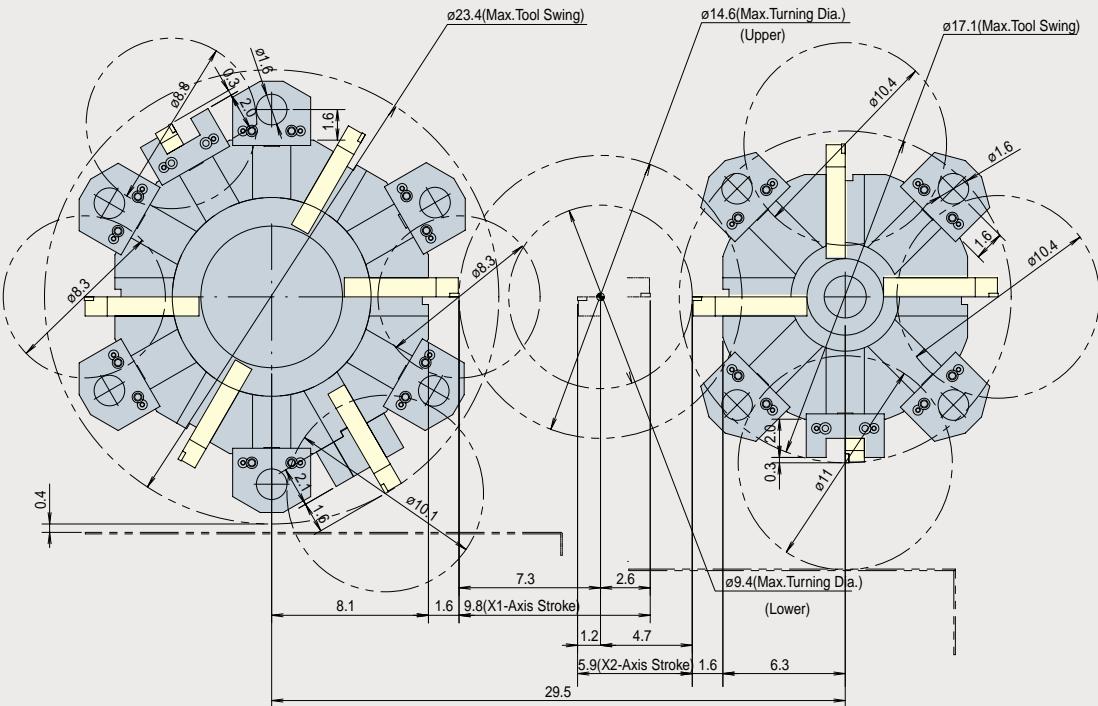
## PUMA TL 2000M/2500M [Option]



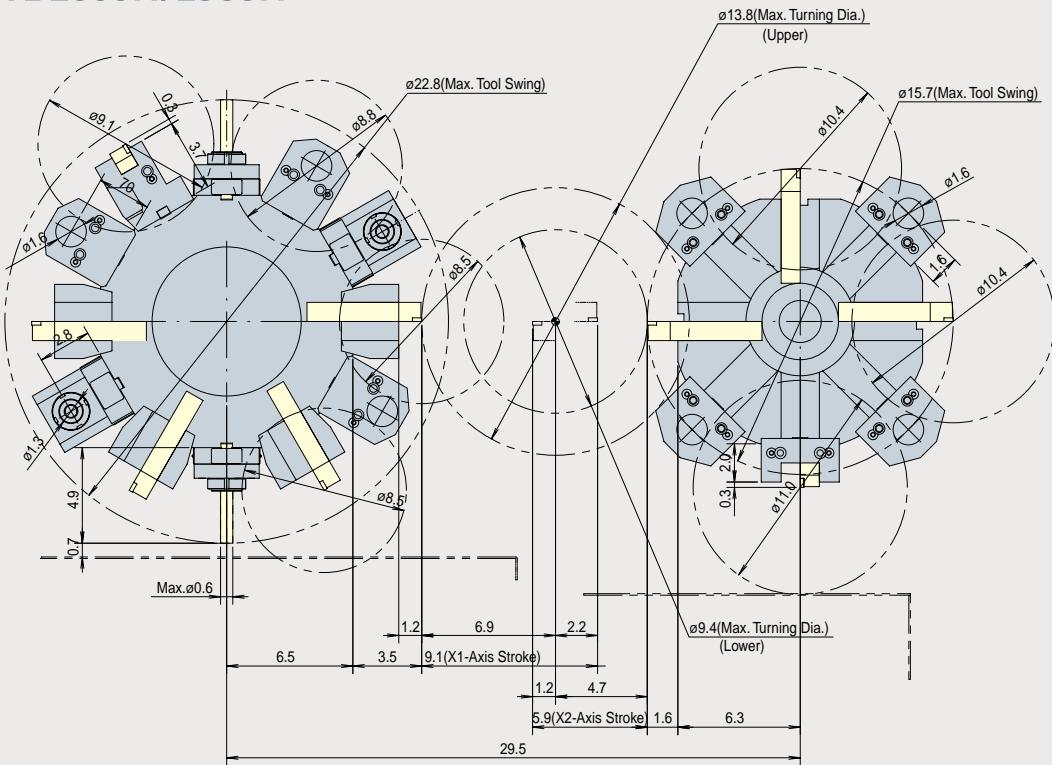
# Tool Interference Diagram

unit : mm

## PUMA TL 2000/2500



## PUMA TL 2000M/2500M

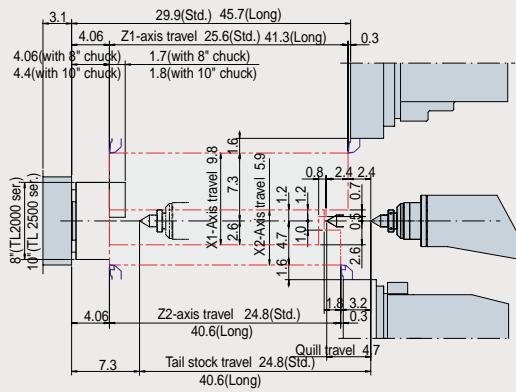


# Working Ranges

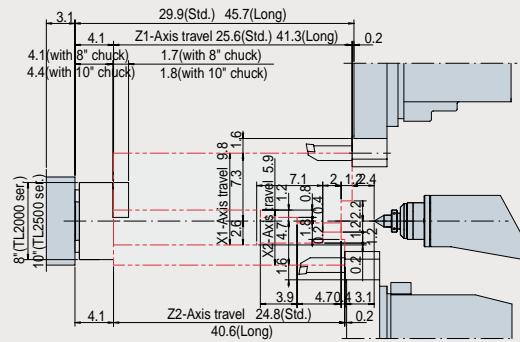
unit : mm

## PUMA TL 2000[L]/2500[L]

### OD tool holder

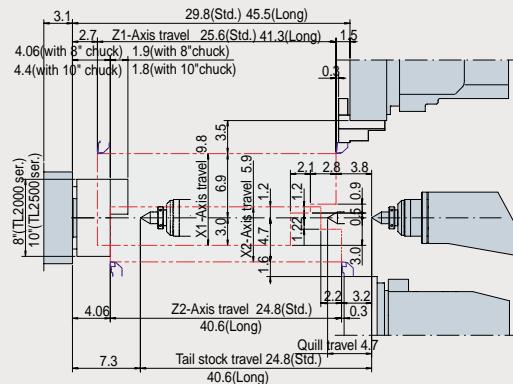


### ID tool holder

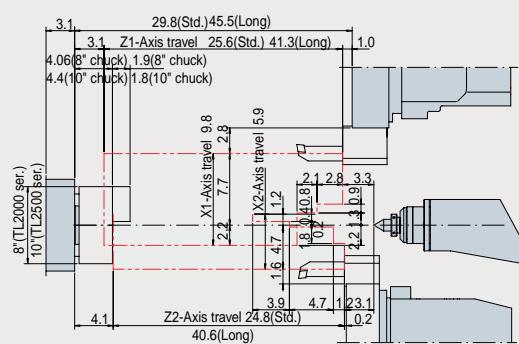


## PUMA TL 2000M[LM]/2500M[LM]

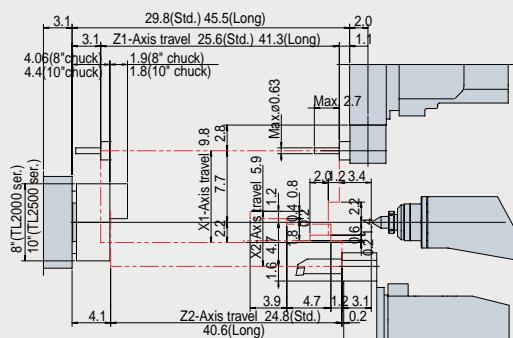
### OD tool holder



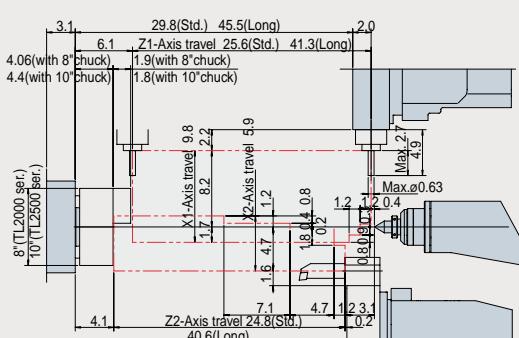
### ID tool holder



### Angular milling tool holder(Option)



### Straight milling tool holder(Option)

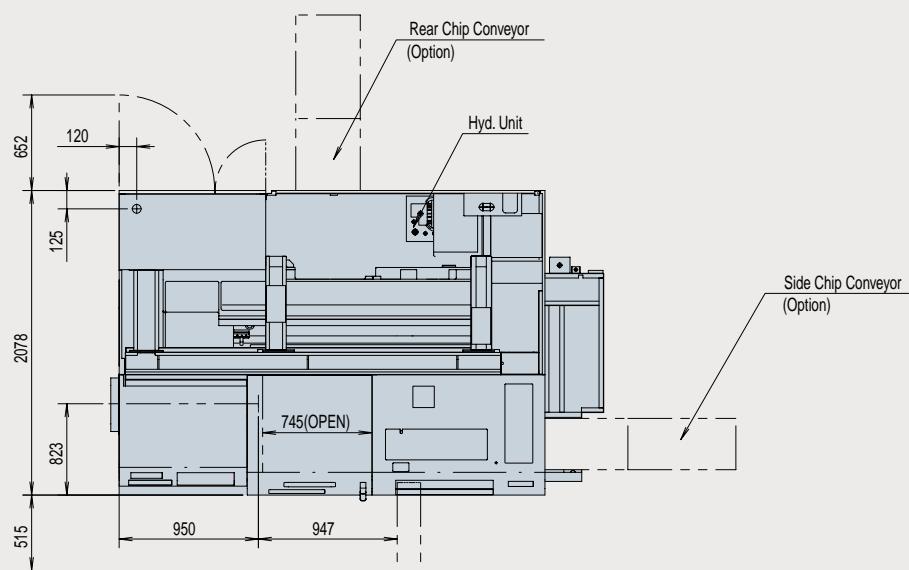


# External Dimension

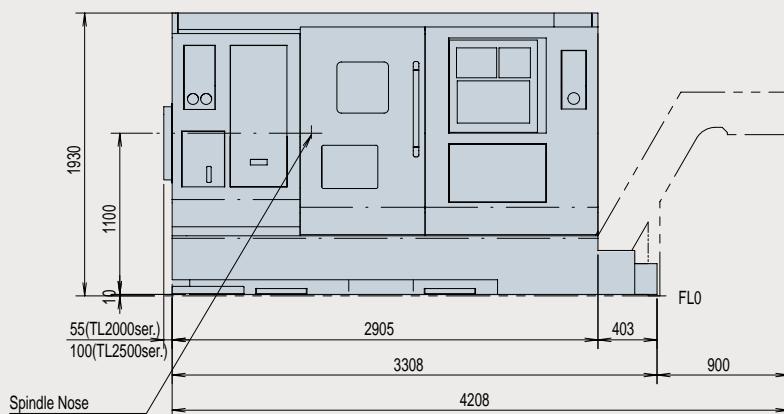
unit : mm

## PUMA TL 2000/2500

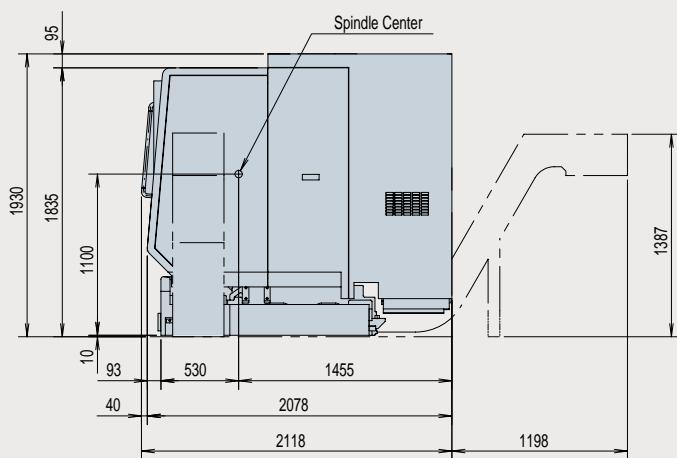
### Top View



### Front View



### Side View

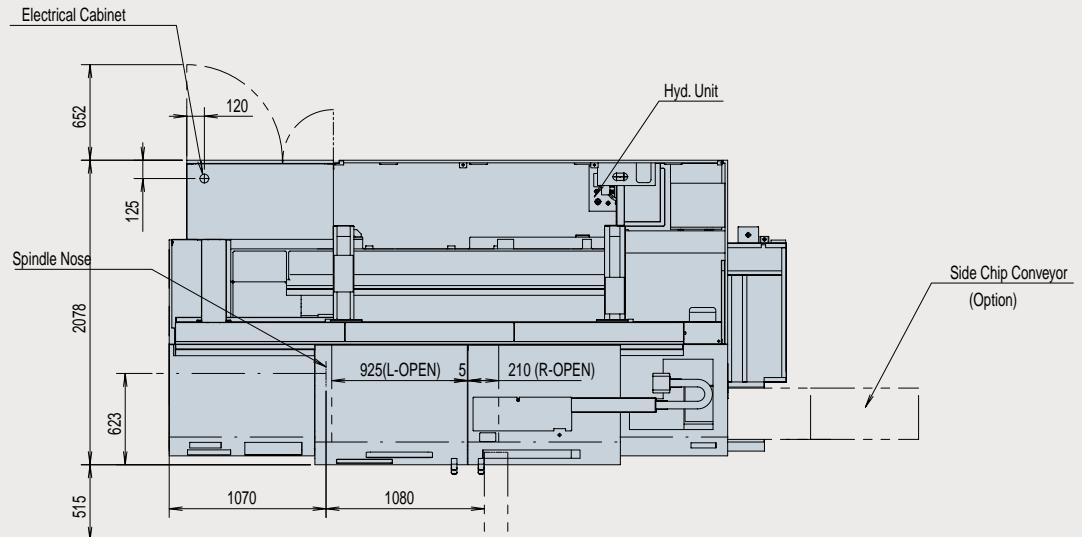


# External Dimension

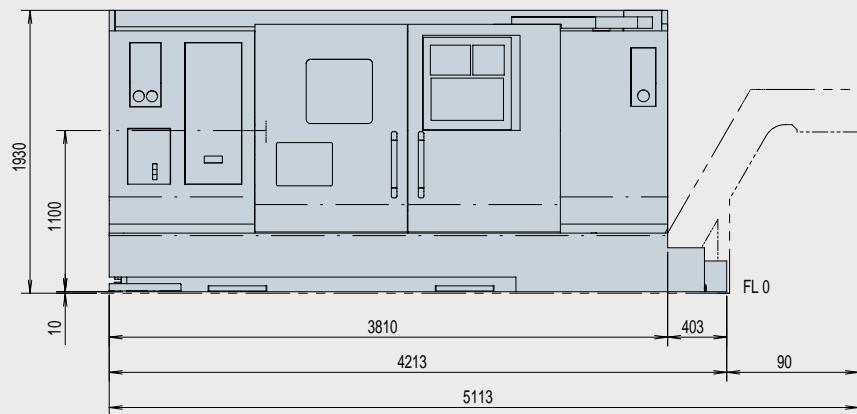
unit : mm

## PUMA TL 2000L/2500L

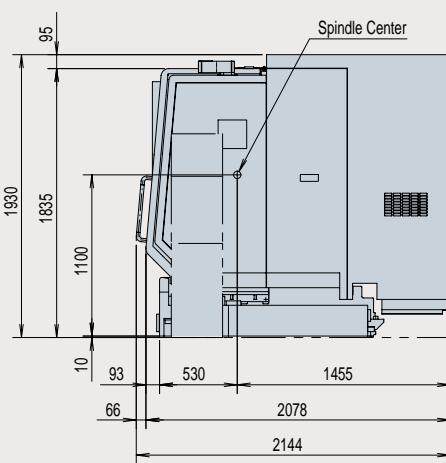
### Top View



### Front View



### Side View



# Machine Specifications

Description		Unit	PUMA TL2000 [L]		PUMA TL2000M [LM]		PUMA TL2500 [L]		PUMA TL2500M [LM]		
<b>Capacity</b>	Swing over bed	mm			600						
	Swing over saddle(Upper)	mm			430						
	Recom. Turning diameter	mm	210		255						
	Max. Turning diameter(Upper/Lower turret)	mm	370/240		350/240		370/240		350/240		
	Max. Turning length	mm			600 [1000]						
	Bar working diameter	mm	ø65		ø76						
<b>Main Spindle</b>	Spindle speed	r/min	5000		4000						
	Spindle nose	ASA	A2#6		A2#8						
	Spindle bearing diameter (Front)	mm	110		130						
	Spindle through hole	mm	ø76		ø86						
<b>Tail Stock</b>	Cs Spindle Index angle	deg	-		360° (in 0.001°)		-		360° (in 0.001°)		
	Quill diameter	r/min			100						
	Quill bore taper	ASA			MT#5						
<b>Carriage</b>	Quill travel	mm			120						
	Travel distance	X1/2-axis	mm			X1 : 250 / X2 : 150					
		Z1/2-axis	mm			Z1 : 650 [1050] / Z2 : 630 [1030]					
	Rapid traverse	X1/2-axis	m/min			20				24	
<b>Turret</b>	No. of tool stations(Upper+Lower)	st			12 + 8						
	OD tool height	mm			25						
	Boring bar diameter	mm			40						
	Indexing time	s			0.15						
	Rotary tool spindle speed*	r/min	-		5000		-		5000		
<b>Motor</b>	Left spindle motor(Int.)	kW	22 (10min)				26 (30min)				
	Rotary tool spindle motor*	kW	-		5.5		-		5.5		
	Servo motor	X1-axis	kW			3.0					
		X2-axis	kW			1.6					
		Z1-axis	kW			3.0					
		Z2-axis	kW			3.0					
	Coolant pump	kW			0.9						
<b>Other</b>	Electric power supply(Rated capacity)	kVA	42		43		50		52		
	Machine height	mm			1930						
	Machine dimensions	length	mm			3250 [3900]					
		width	mm			2118 [2144]					
	Machine weight	kg			7000 [8200]						

Note) [ ] : Long bed machines

\* : Rotary tool spindle is available on only upper turret of TL2000M[LM] / TL2500M[LM].

## Standard Feature

Absolute positioning encoder	Hand tool kit (including small tool for operations)	Safety precaution name plates
Coolant supply equipment	Hydraulic power unit	Spindle oil cooling unit
Foot switch	Leveling jack screw & plates	Standard tool kit (tool holder & boring sleeve )
Front guard door inter lock	Lubrication equipment	Work light
Full enclosure chip and coolant shield	Manuals	

## Optional Feature

Air gun	Chip bucket	Pressure switch for chucking pressure check
Automatic door	Collet chucks*	Proximity switches for chuck clamp detection
Automatic door with safety device	Dual chucking pressure	Signal tower (yellow, red, green)
Automatic power off	Hardened & ground jaws	Tail stock quill for built-in (dead) center
Automatic measuring system*(in process touch probe)	Hydraulic steady rest on lower turret	Tool monitoring system
Air blast for chuck jaw cleaning	Minimum quantity lubrication (MQL) system	Tool pre-setter(manual type, or auto type-renishaw mode)
Bar feeder interface	Oil skimmer	
Bar fuller	Parts catcher	

• Design and specifications are subject to change without prior notice.

• Doosan is not responsible for difference between the information in the catalogue and the actual machine.

## NC Unit Specifications (DOOSAN Fanuc i series)

<b>AXES CONTROL</b>	
- Control paths	2 path
- Control axes	X1, Z1, C1, X2, Z2
X1, Z1, X2, Z2 (TTL 2000/LM/2500/LM)	
X1, Z1, C1, X2, Z2 (TTL 2000/LM/2500/LM)	4 axes
- Simultaneous controlled axes	
- Axis control by PMC	
- Backlash compensation	0 ~ ± 9999 pulses
- Backlash compensation for each rapid traverse and cutting feed	
- Chamfering on/off	
- Cs contouring control	
- Emergency stop	
- Follow-up	
- HRV2 control	
- Inch / Metric conversion	
- Increment system 1/10	0.0001 / 0.00001 mm/inch
- Interlock	All axes / each axis
- Least input command	0.001 / 0.0001 mm/inch
- Machine lock	All axes / each axis
- Mirror image	
- Overtravel	
- Position switch	
- Servo off	
- Strode stroke check 1	
- Strode stroke check 2, 3	
- Torque control	
- Unexpected disturbance torque detection function	
- Stroke limit check before move	
- Strode pitch error compensation	
<b>OPERATION</b>	
- Automatic operation (memory)	
- MDI operation	
- DNC operation	
- Buffer register	
- Dry run	
- Handle incremental feed	X1, X10, X100
- Manual Handle interruption	
- Program restart	
- JOG feed	
- Manual handle feed	1 unit
- Manual pulse generator	1 ea
- Manual reference position return	
- Program number search	
- Reference position shift	
- Reference position setting without dog	
- Sequence number search	
- Single block	
- Wrong operation prevention	
<b>INTERPOLATION FUNCTIONS</b>	
- Nano interpolation	
- Positioning	G00
- 1st Reference position return	Manual, G28
- 2nd Reference position return	G50
- 3rd / 4th Reference position return	

- Balance cutting	
- Circular interpolation	G02
- Continuous threading	
- Cylindrical interpolation	
- Dwell (per sec)	G04
- High Speed Skip Function	
- Linear interpolation	G01
- Multiple threading	
- Polar coordinate interpolation	
- Polygon turning	
- Polygon Turning With Spindles	
- Reference position return check	G27
- Skip	G31
- Thread cutting / Synchronous cutting	
- Thread cutting extract	
- Thread cutting rate	
- Torque limit skip	
- Variable lead threading	
<b>FEED FUNCTION</b>	
- Automatic acceleration / deceleration	
- Cutting feedrate clamp	
- Feed per minute	
- Feed per revolution	
- Feedrate override (10% unit)	0 - 200 %
- Jog feed override (10% unit)	0 - 2000 mm/min
- Manual per revolution feed	
- Overdrive cancel	
- Rapid traverse override	F0, 25, 100 %
- Rapid traverse rate	
- Tangential speed constant control	
<b>AUXILIARY / SPINDLE SPEED FUNCTION</b>	
- Spindle orientation	
- Actual spindle speed output	
- Auxiliary function lock	
- Constant surface speed control	
- High speed M/S/T interface	
- M - code function	M3 digits
- Multi spindle control	
- Rigid tapping	
- S - code function	S4 / \$5 digits
- Spindle serial output	S4 / \$5 digits
- Spindle speed override	0 - 150 %
- Spindle Output switching	
- Waiting function	
<b>PROGRAM INPUT</b>	
- Absolute / incremental programming	
- Additional Macro Variables	#100-#199, #500-#999
- Automatic coordinate system setting	
- Canned cycle for drilling	
- Canned cycle	
- Circular interpolation by R programming	
- Control in / out	
- Coordinate system setting	G50
- Coordinate system shift	
- Custom macro	
- Decimal point programming /	
- Pocket calculator type decimal point programming	
- Diameter / radius programming (X axis)	
- Direct drawing dimension programming	
- Direct input of coordinate system shift	
- G code system A / B / C	
- Input unit 10 time multiply	
- Label skip	
- Manual absolute on and off	
- Max. programmable dimension	± 9 digit
- Multiple repetitive cycle	G70 - G76
- Multiple repetitive cycle II	
- Optional block skip	9 pieces
- Parity check	
- Plane selection	G17, G18, G19
- Program stop / end (M00, M01 / M02, M30)	
- Programmable data input	G10
- Sequence number	N5 digit
- SUB program call	10 folds nested
- Tape code	EIA / ISO
- Tape format for FANUC Series10/11	
- Work coordinate system	G52 - G59
- Work coordinate system	
- Interruption type custom macro	
- Chamfering / Corner R	
<b>TOOL FUNCTION / TOOL COMPENSATION</b>	
- Automatic tool offset	
- Direct input of offset value measured	
- Direct input of offset value measured B	
- T - code function	T2 + 2 digits
- Tool geometry / wear compensation	
- Tool life management	
- Tool radius / Tool nose compensation	
- Tool offset	G43, G44, G49
- Number of Tool Offsets	200 pairs
- Tool offset value counter input	
- Tool Load Monitoring system	
<b>EDITING OPERATION</b>	
- Background editing	
- Memory card edit & operation	
- Extended part program editing	
- Number of registered programs	400 ea
- Part program editing	
- Part program storage size	1280m (512kB)
(Note) Specify total of part program storage size of each path	
- Program protect	
- Playback function	
<b>SETTING AND DISPLAY</b>	
- Actual cutting feedrate display	
- Alarm display	
- Alarm history display	
- Current position display	
- Directory display and punch for each group	
- Directory display of floppy cassette	
- Periodic maintenance screen	
- Display of spindle speed and T code at all screens	
- Help function	
- Optional path name display	
- Multi-language display	
- Operation history display	
- Parameter setting and display	
- Program comment display	31 characters
- Run hours / part count display	
- Self-diagnosis function	
- Servo setting screen	
- Spindle setting screen	
- Status display	
- External key input	
- External data input	
- Operating monitor screen	
- Servo waveform display	
<b>DATA INPUT / OUTPUT</b>	
- External program input	
- External program number search	
- External work number search	
- Memory card input/output	
- Reader / puncher interface	
- RS232C interface	
- Automatic data backup	
<b>OTHERS</b>	
- Cycle start and lamp	
- Display unit	10.4" Color TFT LCD
- Feed hold and lamp	
- PCMCIA port in the front of LCD display unit	
- NC and servo ready	
- PMC system	0iD-PMC
- Reset / rewind	
<b>INTERFACE FUNCTION</b>	
- Ethernet function	Embedded ethernet
<b>OPERATION GUIDANCE FUNCTION</b>	
- EZ_Guide (Conversational Programming Solution)	
<b>OPTIONAL SPECIFICATIONS</b>	
<b>OPERATION</b>	
- Manual tool retract and return	
<b>INTERPOLATION FUNCTIONS</b>	
- Multi step skip	
- Helical interpolation	
<b>FEED FUNCTION</b>	
- Advanced preview control	
<b>DATA INPUT / OUTPUT</b>	
- Fast ethernet	
- Data server	
<b>CONTOURING FUNCTION</b>	
- AIGC	30 blocks
<b>ROBOT INTERFACE</b>	
- Robot interface with PMC I/O module	
(Hardware between PMC I/O modules)	
- Robot interface with PROFIBUS-DP	

## NC Unit Specifications (Fanuc 31i-A)

<b>AXES CONTROL</b>		2 path
- Control paths	X1, Z1, X2, Z2 (TL 2000/L/2500/L)	
- Control axes	X1, Z1, C1, X2, Z2 (TL 2000/LM/2500/LM)	
- Simultaneous controlled axes		4 axes
- Axis control by PMC		
- Backlash compensation		0 ± 9999 pulses
- Backlash compensation for each rapid traverse and cutting feed		
- Chamfering on/off		
- Cs contouring control		
- Emergency stop		
- Follow-up		
- HRV2 control		
- Inch / Metric conversion		
- Interlock	All axes / each axis	
- Least input command	0.001 / 0.001 mm/inch	
- Machine lock	All axes / each axis	
- Mirror image		
- Over travel		
- Position switch		
- Servo off		
- Stored stroke check 1		
- Unexpected disturbance torque detection function		
- Stored pitch error compensation		
<b>OPERATION</b>		
- Automatic operation (memory)		
- MDI operation		
- DNC Operation with Memory card		
- Buffer register		
- Dry run		
- Incremental feed	X1, X10, X100	
- Program restart		
- Wrong operation prevention		
- JOG feed		
- Manual handle feed	1 unit	
- Manual pulse generator	1 ea	
- Manual reference position return		
- Program number search		
- Reference position setting without dog		
- Sequence number search		
- Single block		
- Reference position shift		
<b>INTERPOLATION FUNCTIONS</b>		
- Nano interpolation		G00
- Positioning		G01
- 1st_Ref. position return		Manual, G20
- 2nd_Ref. position return		G30
- Balance cutting		
- Circular interpolation		G02
- Continuous threading		
- Cylindrical interpolation		
- Dwell (per sec)		G00
- Linear interpolation		G01
- Multi threading		
- Polar coordinate interpolation		
- Reference position return check		G27
- Skip		G31
- Thread cutting / Synchronous cutting		

- Thread cutting retrace	Word coordinate system	G52 - G59
<b>FEED FUNCTION</b>		
- Automatic acceleration / deceleration	- Automatic tool offset	
- Cutting feedrate clamp	- Direct input of offset value measured	
- Feed per minute	- Direct input of offset value measured B	
- Feed per revolution	- T - code function	T2 + 2 digits
- Feedrate override (10% unit)	- Tool geometry / wear compensation	
0 - 200 %	- Tool life management	
Jog feed rate (10% unit)	- Tool nose radius compensation	
0 - 2000 mm/min	- Tool offset	G43, G44, G49
Manual per revolution feed	- Number of Tool Offsets	64 pairs
Override cancel	- Tool offset value counter input	
Rapid traverse override	- Tool Load Monitoring system	
F0, 25, 100 %	<b>EDITION OPERATION</b>	
Tangential speed constant control	- Back ground editing	
<b>AUXILIARY / SPINDLE SPEED FUNCTION</b>	- Memory card edit & operation	
- Spindle orientation	- Extended part program editing	
- Actual spindle speed output	- Number of registered programs	500 ea
- Constant surface speed control	- Part program editing	
- High speed M/S/T interface	- Part program storage size	256 Kbyte
M - code function	(Note) Specify total of part program storage size of each path	
- Multi spindle control	- Program protect	
Rigid tapping		
S - code function		
Spindle serial output		
Spindle speed override		
0 - 150 %		
Spindle Output switching		
Waiting function		
<b>PROGRAM INPUT</b>		
- Absolute / incremental programming	- Actual cutting feedrate display	
- Automatic coordinate system setting	- Alarm display	
- Canned cycle for drilling / Turning	- Alarm history display	
- Canned cycle for turning	- Current position display	
- Circular interpolation by R programming	- Periodic maintenance screen	
- Control in/out	- Display of spindle speed and T code at all screens	
- Coordinate system setting	- Help function	
- Coordinate system shift	- Optional path name display (Only for 2path)	
- Custom macro	- Multi-language display	English
- Decimal point programming /	- Operation history display	
Pocket calculator type decimal point programming	- Parameter setting and display	
- Diameter / radius programming (X axis)	- Program comment display	31 characters
- Direct drawing dimension programming	- Run hours / part count display	
- Direct input of coordinate system shift	- Self-diagnosis function	
G code system A	- Servo setting screen	
- Input unit 10 time multiply	- Spindle setting screen	
- Label skip	- Status display	
- Macro executor	- Operating monitor screen	
- Manual absolute on and off	- Servo waveform display	
- Max. programmable dimension	- Directory display of floppy cassette	
±9 digit		
- Multiple repetitive canned cycle		
G70 - G76		
- Multiple repetitive canned cycle II		
Optional block skip		
9 pieces		
Parity check		
Plane selection		
G17, G18, G19		
Program file name		
32 characters		
Program stop / end (M00, M01 / M02, M30)		
Programmable data input		
G10		
Sequence number		
N8 digit		
SUB program call		
10 folds nested		
Tape code		
EIA / ISO		
Tape forms for FANUC Series15		
<b>OTHERS</b>		
- Cycle start and lamp	- Display unit	10.4" Color TFT LCD
- Display unit	- Feed hold and lamp	
- Sequence number	- MIDI unit	
N8 digit	- NC and servo ready	
SUB program call	- PMC system	31iA-PMC
10 folds nested		
Tape code		
EIA / ISO		
Tape forms for FANUC Series15		
<b>TOOL FUNCTION / TOOL COMPENSATION</b>		
- Automatic tool offset	- Reset / rewind	
- Direct input of offset value measured	- Ethernet function	Embedded ethernet
- Direct input of offset value measured B		
- T - code function	<b>INTERFACE FUNCTION</b>	
	- AIGC I	
	- AIGC II	30 blocks
	<b>OPERATION GUIDE FUNCTION</b>	
	- EZ Guide (Conversational Programming Solution)	
<b>OPTIONAL SPECIFICATIONS</b>		
<b>AXIS CONTROL</b>		
- Chuck and tail stock barrier	- Stored stroke 2 and 3	
- Stored limit check before move		
<b>OPERATION</b>		
- DNC operation	- Manual handle feed	2 units
- Handle interruption	- Tool retract and recover	
- Real time custom macro	- Active block function	
- Change active offset with manual move	- Manual tool retract and return	
<b>INTERPOLATION FUNCTIONS</b>		
- 3rd / 4th reference position return	- Circular threading	
- Multi step skip	- Polygon Thinning with Spindles	
- Helical interpolation	- High Speed Skip Function	
<b>FEED FUNCTION</b>		
- External deceleration		
- Feed stop		
<b>PROGRAM INPUT</b>		
- Work Coordinate System		48 / 300 pairs
- Automatic corner override		
- Interrupt type custom macro		
- Pattern data input		
- Work coordinate system preset		
- Chamfering / corner R		
- Additional macro variables	#100~#199, #500~#999	
<b>TOOL FUNCTION / TOOL COMPENSATION</b>		
- Addition of tool pairs for tool life management		
- Number of Tool Offsets	99/200/400/499/999/2000 pairs	
<b>EDITING OPERATION</b>		
- Number of registered programs & Part program storage length		
1280M (512KB) 1000 ea	2560M (1MB) 1000 ea	
20480M (8MB) 4000 ea	20480M (8MB) 1000 ea	
1280M (512KB) 1000 ea	10240M (4MB) 4000 ea	
10240M (4MB) 1000 ea	5120M (2MB) 4000 ea	
5120M (2MB) 1000 ea	640M (256KB) 500 ea	
	2560M (1MB) 2000 ea	
<b>PLAYBACK FUNCTION</b>		
<b>DATA INPUT / OUTPUT</b>		
Fast ethernet / Data server		Only for 1 path
<b>CONTOURING FUNCTION</b>		
- AIGC I		
- AIGC II		30 blocks
<b>ROBOT INTERFACE</b>		
- Robot interface with PMC I/O module		
- Hardware interface with PMC I/O modules		
- Robot interface with PROFIBUS-DP		

# PUMA TL 2000/2500

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